

Artificial Intelligence–Powered Ultrasound for Improving Clinical Workflow

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ABSTRACT: *Ultrasound is the most commonly used imaging modality in clinical practice because it is a nonionizing, low-cost, and portable point-of-care imaging tool that provides real-time images. Artificial intelligence (AI)–powered ultrasound is becoming more mature and getting closer to routine clinical applications in recent times because of an increased need for efficient and objective acquisition and evaluation of ultrasound images. Because ultrasound images involve operator-, patient-, and scanner-dependent variations, the adaptation of classical machine learning methods to clinical applications becomes challenging. With their self-learning ability, deep-learning (DL) methods are able to harness exponentially growing graphics processing unit computing power to identify abstract and complex imaging features. This has given rise to tremendous opportunities such as providing robust and generalizable AI models for improving image acquisition, real-time assessment of image quality, objective diagnosis and detection of diseases, and optimizing ultrasound clinical workflow. In this report, the authors review current DL approaches and research directions in rapidly advancing ultrasound technology and present their outlook on future directions and trends for DL techniques to further improve diagnosis, reduce health care cost, and optimize ultrasound clinical workflow.*

Key Words: *Artificial intelligence in ultrasound, deep learning in ultrasound, thyroid nodule, breast lesion, liver lesion*

I. INTRODUCTION

Artificial intelligence (AI)–powered ultrasound is becoming more mature and coming closer to routine clinical applications in recent years because of an increased need for efficient and objective acquisition and evaluation of ultrasound images. Because ultrasound is an operator-dependent imaging modality, it is important to develop deep-learning (DL) models that assess image quality and provide feedback to sonographers; providing guidance during data acquisition and measurement makes ultrasound more intelligent and less operator dependent.

In this review, we intend to give an overview of the advances in AI-powered ultrasound that create opportunities to objectively evaluate ultrasound data, improve clinical workflow, and reduce health care costs. We also provide a brief background on DL and ultrasound imaging to give a comprehensive insight into the field. Afterward, we present currently available DL applications in ultrasound, discuss challenges, and present our outlook on future directions in AI-powered ultrasound.

DL

DL is a subset of machine learning (ML) and AI that extracts a complex hierarchy of features from images by its self-learning ability, as opposed to the handcrafted feature extraction in classical ML algorithms [1]. DL involves neural networks with many layers that extract a hierarchy of features from raw input images. The rapid increase in the processing power of graphics processing units has enabled the development of state-of-the-art DL algorithms that can be trained with millions of images and are robust to variations in images. DL has become popular because of recent successes especially in image segmentation and classification applications. Compared with DL, classical ML approaches that are hand designed in decomposable pipelines are more interpretable because each component has an explanation, but they are usually not very accurate or robust. By using DL models we sacrifice interpretability for robust and complex imaging features with greater generalization ability.

Several types of DL approaches have been developed for different purposes, such as object detection and segmentation in images, speech recognition, genotype and phenotype detection, and classification of

diseases. Some of the popular DL algorithms are stacked autoencoders [2], deep Boltzmann machines, deep-belief neural networks [3], and convolutional neural networks (CNNs) [4]. CNNs are the algorithms most commonly applied to images. Since their first introduction in 1989 [5], CNNs have been widely applied to classification and segmentation of photographic images with great success [4,6,7].

DL techniques achieve impressive results and robustness by training on large amounts of data. They are also gaining popularity in many areas of medical image analysis [8], such as tissue and lesion segmentation [1,9-13], lesion diagnosis [1,14-18], and histopathologic analysis [19,20]. CNN architectures are increasingly complex, with some systems having more than 100 layers, which means millions of weights and billions of connections among neurons. A typical CNN architecture contains multiple convolution, max-pooling, and activation layers. Convolutional layers produce feature maps by convolving a convolutional kernel across the input image. Max-pooling is used to down-sample the output of convolutional layers by passing the maximum value of a defined neighborhood to the next layer. Rectified linear unit is one of the most commonly used activation functions. It nonlinearly transforms data by clipping any negative input values to zero, while positive input values are passed as output [21]. To perform a prediction from input data, the output scores of final CNN layer are connected to a softmax nonlinearity function that normalizes scores into multinomial distribution over labels. Also, an optimizer that minimizes the error between prediction and ground-truth labels through a loss function and a gradient backpropagation method that updates weights at each iteration are used to train CNN architectures until they converge to steady state (see Fig. 1).

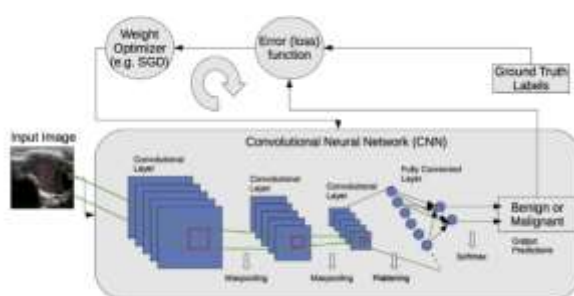


Fig 1. A schematic illustration of a deep-learning training process for a classification task. White arrows show operations between layers. CNN ¼ convolutional neural network; SGD ¼ stochastic gradient descent.

Ultrasound Imaging

Diagnostic ultrasonography is an ultrasound-based imaging technique used for visualizing and diagnosing pathological changes of internal organs such as liver, heart, and vessels and superficial structures such as thyroid, breast, and muscles. Ultrasound has several advantages compared with other medical imaging techniques. It is safe because it does not use harmful ionizing radiation, like radiography and CT, it is considerably lower in cost, it is portable for point-of-care applications, and it provides real-time imaging. Because it is portable, it can be transported to a patient’s bedside and is useful for patient screening and follow-up. The disadvantages of ultrasound include its strong operator dependence and inability to examine areas of the body containing gas and bones. The most common types of ultrasound images are shown in Figure 2.

II. METHODS

We performed a thorough analysis of the literature using the Google Scholar and PubMed search engines. We included 31 peer-reviewed journal publications and conference proceedings in this field (Medical Image Analysis, IEEE Transactions on Medical Imaging, IEEE Journal of Biomedical and Health Informatics, Medical Physics, Ultrasonics, and conference proceedings from SPIE, the Medical Image Computing and Computer Assisted Intervention Society, the Institute of Electrical and Electronics Engineers, and others) that describe the application of DL to ultrasound before January 15, 2019 (see Fig. 3 for the identification and selection procedure). We divided reports into four groups on the basis of the frequency of studies in the literature, namely, studies on thyroid, breast, liver, and other areas.

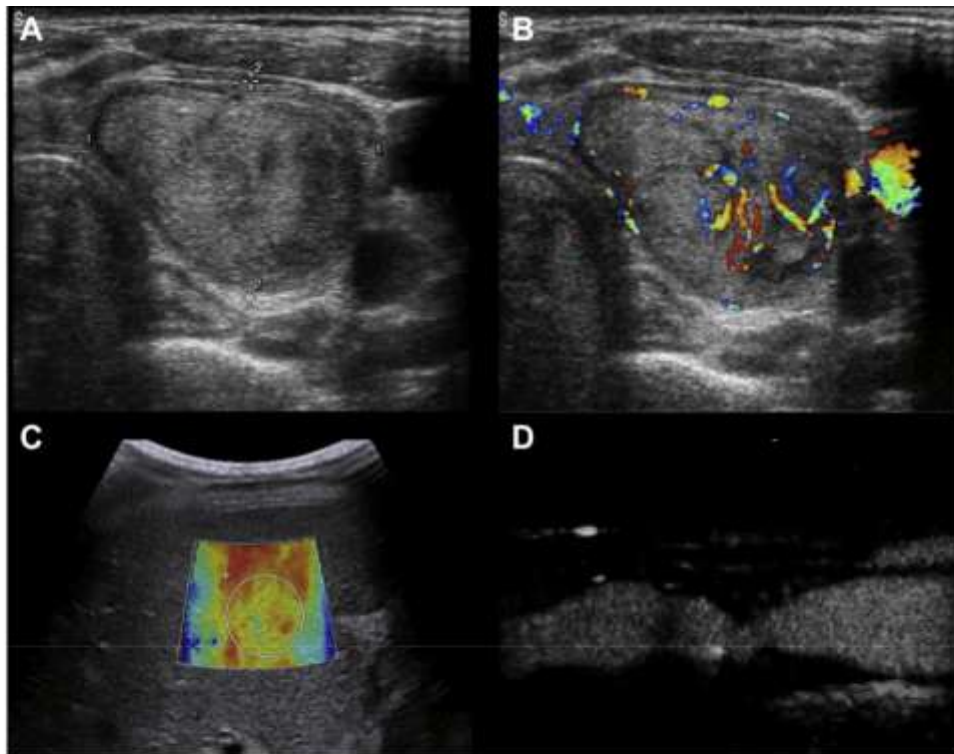


Fig 2. Examples of ultrasound images. (A) B-mode image of a thyroid nodule. (B) Color flow Doppler image of a thyroid nodule overlaid on B-mode image. (C) Shear-wave elastographic map overlaid on B-mode image of a liver with stage F3 fibrosis. (D) Contrast-enhanced ultrasound image of a carotid artery with stenosis.

Training, Validation, and Evaluation

In DL, data are divided into training, validation, and test sets to learn from examples, establish the soundness of learning results, and evaluate the generalizability of a developed algorithm on unseen data, respectively. When there are limited data, cross-validation methods (eg, k-fold) are preferred. Training is typically done with a supervised approach, which requires ground truth for the

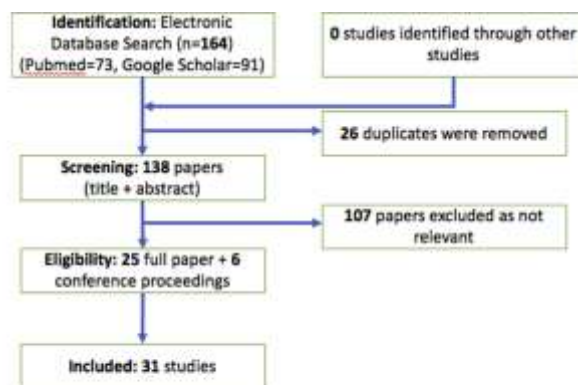


Fig 3. Flowchart for identification, screening, eligibility, and inclusion of studies.

task. Most DL applications involve supervised learning, in which a DL model is trained on a data set of images with provided ground-truth labels or segmentation maps. Ground truth is usually obtained with manual delineations of lesions or structures by experts for segmentation tasks.

The optimal way to compare the performance of DL models presented in each application is to evaluate them on data sets that are publicly available with well-accepted ground truth. However, this is a big challenge in this field. We have presented the performance of each DL model on the reported validation and test data sets for each application in the “Results” section.

AI-Powered Detection, Segmentation, and Diagnosis in Ultrasound

Computer-aided diagnosis (CAD) has become one of the major research subjects in diagnostic radiology. CAD provides a second opinion to assist radiologists in image interpretation by improving the accuracy and consistency of radiologic diagnosis and also by reducing image reading time. Many ultrasound CAD systems that are mainly for breast, thyroid, and liver disease detection and classification have been proposed in the past 2 decades. The majority of these CAD systems are based on classical ML using texture features that include several processing steps: preprocessing, feature extraction and selection, and classification. Even though these studies show the promise of ultrasound CAD, they include several limitations: subjective selection of a region of interest that includes pathology, using limited training and test data sets, and having data that are collected only from a single ultrasound device at a single medical center. These limitations make it difficult to integrate ML algorithms on the basis of textures into clinical workflow to assist radiologists. In recent years, researchers have proposed DL-based ultrasound CAD systems following the success of DL in image classification and segmentation tasks [15,22]. Knowledge gained from one data set could be easily transferred to a new data set obtained from another center with another ultrasound device by fine-tuning the DL model on a new data set, which is called transfer learning.

Thyroid Nodule Detection and Classification

Thyroid nodules are extremely common lesions and are found in 50% of the adult population on the basis of autopsy studies [23-26]. The only nonsurgical test that is proven to differentiate a benign from a malignant nodule is fine-needle aspiration biopsy. Because the majority of thyroid nodules selected for fine-needle aspiration (w90%) are benign [27,28], a noninvasive and reliable method is necessary to identify nodules that do not require biopsy or surgery. This will significantly reduce health care costs and patient anxiety. To be acceptable, sensitivity at or near 100% is needed to make sure cancers are not missed with a reasonable specificity so that a good fraction of benign lesions is not biopsied.

Ma et al [29] presented a method based on the fusion of two customized CNN models that includes 7 7, 5 5, and 3 3 convolutional kernels to classify benign and malignant nodules. It was validated on 15,000 images collected from two local hospitals. In another study, Ma et al [30] presented a cascaded CNN model that includes two consecutive CNN models with 15 and 4 convolutional layers. It automatically detects nodules from ultrasound B-mode images in two steps. They evaluated their model with 10-fold cross-validation. Li et al [31] used Faster R-CNN [32] (which achieved best performance on the The PASCAL Visual Object Classes data set) to automatically detect papillary carcinoma and benign regions of nodules from ultrasound B-mode images. Li et al [33] presented a retrospective and multicohort study with a large population from three hospitals (332,180 images from 45,644 patients in total). They used Resnet50 [34] and Darknet [35] CNN models pretrained on the ImageNet dataset. Akkus et al

[16] presented a CNN model [36] using an attention map to predict nodules from ultrasound B-mode images. Choi et al [22] used a proprietary CAD system (S-Detect for Thyroid; Samsung Medison, Seoul, South Korea) to classify 102 nodules from 89 patients as benign or malignant. Pereira et al [37] compared DL approaches for thyroid nodule characterization from shear wave elastographic (SWE) images. Chi et al [17] fine-tuned a GoogleNet [36] model to classify thyroid nodules and tested it on a data set of 61 cases.

Breast Lesion Detection and Classification

Breast cancer is the most frequent cancer among women and also the leading cause of cancer-related deaths among women [38]. The BI-RADS [39] score is used to standardize reporting and reduce confusion in breast imaging interpretations. However, significant intra- and interobserver variability on the basis of BI-RADS scoring has been reported in several studies [40,41]. CAD systems with high sensitivity and negative predictive value can be used to provide radiologists a second opinion in a cost-effective way and can help reduce unnecessary false-positive biopsies. To date, several DL approaches have been explored for objective and reproducible classification of breast lesions from ultrasound images. Byra et al [42] presented a CNN model based on transfer learning to classify breast lesions as benign or malignant. They used the VGG19

[43] CNN model pretrained on the ImageNet data set and fine-tuned it on 882 ultrasound images of breast masses. Han et al [44] trained a GoogleNet [36] model on 7,408 breast ultrasound images and tested on 829 images. This model is a component algorithm of S-Detect technology, which is implemented in RS80A (Samsung Medison). Cheng et al [15] used a stacked denoising autoencoder model [2] to classify breast lesions. Zhang et al [45] used a two-layer DL model that includes a fully connected neural network as the first layer to extract features and a restricted Boltzmann machine as the second layer to provide better feature representation. A support vector machine (SVM) classifier was connected to the restricted Boltzmann machine to predict breast lesions. Several other studies also used DL to detect breast lesions from ultrasound images [46,47].

Liver Lesion Classification

Ultrasound is the preferred imaging modality to evaluate liver diseases because it provides information about the appearance of the liver and portal venous blood flow. Although liver biopsy is sensitive in assessing cirrhosis, it is invasive and limited by sampling errors, interobserver variability, and various potential complications such as damage to the lung and gallbladder, bleeding, and infection. Wang et al [49] presented a multicenter study to assess liver fibrosis stage with DL from ultrasound SWE images. They concluded that DL-based elastography is more accurate than 2-D SWE imaging in assessing cirrhosis and advanced fibrosis and more accurate than biomarkers in assessing all three liver fibrosis stages in patients with chronic hepatitis B. Meng et al [50] used a fine-tuned VGGNet [43] and fully connected network based on transfer learning to predict the stage of liver fibrosis. Similarly, Liu et al [51] presented a pretrained CNN model that extracts features of liver capsule from ultrasound images and uses an SVM to classify a liver as normal or abnormal from extracted CNN features. Wu et al [52] trained a deep-belief network model [3] on time-intensity curves extracted from contrast-enhanced ultrasound for the classification of focal liver lesions. They showed that their method outperforms classical ML methods. Biswas et al [53] assessed fatty liver disease from ultrasound images using DL and achieved a performance superior to that of ML approaches.

Other Applications

In addition to three main applications of DL in ultrasound, several other AI applications in ultrasound have been explored by researchers in the field. Yu et al [55] used a customized CNN that contains 16 convolutional layers with 3x3 kernels and three fully connected layers to classify the fetal ultrasound plane. Wu et al [56] assessed the quality of fetal ultrasound images using two cascaded CNN models for accurate measurements. The first CNN (pretrained AlexNet) finds the region of interest of the abdominal region from ultrasound images. The second CNN that receives the region of interest from the first CNN as input evaluates the image quality by assessing the key structures of stomach bubble and umbilical vein. Chen et al [57] also used a composite CNN framework that includes a CNN model for in-plane feature extraction and long short-term memory model to classify fetal standard planes. Menchón-Lara et al

[58] used an autoencoder [2] to segment intima-media thickness in a user-independent and reproducible manner. Lekadir et al [59] used a CNN that includes four convolutional and three fully connected layers to classify atherosclerotic plaque components including lipid core, fibrous tissue, and calcified tissue. Hetherington et al

[60] presented a spine-level vertebra identification system using pretrained CNN models. Cheng and Malhi [61] used the VGG model [43] to classify the anatomic location and plane of abdominal ultrasound images. DL has been also used for ultrasound beamforming [62,63], image recovery [64], image reconstruction from subsampled RF data [65], and elastographic image reconstruction [66].

III. RESULTS

Thyroid Nodule Detection and Classification

Ma et al [29] validated their CNN model on 15,000 images collected from two local hospitals and achieved accuracy of 83.02 ± 0.72% for classifying benign and malignant nodules. However, their receiver operating characteristic (ROC) curve indicated that their model always missed some malignant cases and never reached 100% sensitivity. Ma et al [30] evaluated their nodule detection model with 10-fold cross-validation and achieved an average area under the ROC curve (AUC) of 98.51%. The CNN model of Li et al [31] for detecting papillary carcinoma and benign regions of nodules from ultrasound B-mode images obtained 93.5% sensitivity and 81.5% specificity. Li et al [33] concluded on the basis of a retrospective and multicohort study with a large population from three hospitals (a total of 332,180 images from 45,644 patients) that the CNN model showed similar sensitivity and improved specificity in identifying patients with thyroid cancer compared with a group of skilled radiologists. The performance of the CNN model by Akkus et al [16] on a test set of 100 transverse and longitudinal images of 50 nodules was 86% (sensitivity) and 90% (specificity). When the threshold was set for maximum sensitivity (zero missed cancers), their ROC curve suggests that the number of biopsies may be

reduced by 52% without missing patients with malignant thyroid nodules. Choi et al [22] concluded on the basis of 102 nodules from 89 patients that the sensitivity of the CAD system using AI for malignant thyroid nodules was as good as that of the experienced radiologist. Pereira et al [37] obtained the highest accuracy of 83% on 20% of a data set of 964 images from 165 patients. Chi et al [17] achieved 98.29% accuracy on a test data set of 61 cases for classification of thyroid nodules with a fine-tuned GoogleNet model [36]. Characteristics of each model are summarized in Table 1.

Breast Lesion Detection and Classification

Byra et al [42] achieved an AUC of 93.6% over a test data set of 150 cases for classifications of breast lesions into benign or malignant lesions and concluded that the model has potential to assist radiologists with breast mass classification in ultrasound. Han et al [44] achieved accuracy of 90%, sensitivity of 86%, and specificity of 96% on the test data set (n ¼ 829 images). Cheng et al [15] achieved an AUC of 89.6% for classification of breast lesions, which outperforms conventional ML-based methods. Zhang et al [45] achieved better performance with their two-layer DL model when classifying breast lesions from SWE images (accuracy 93.4% versus 84%-87%). Characteristics of each model are summarized in Table 2.

Liver Lesion Classification

Several studies used DL to diagnose liver diseases from ultrasound images (see Table 3 for a summary). Wang et al [49] concluded that DL-based elastography is more accurate than 2-D SWE imaging in assessing cirrhosis and advanced fibrosis and more accurate than biomarkers in assessing all three liver fibrosis stages in patients with chronic hepatitis B. The AUCs of the proposed method were 97% for F4 (cirrhosis), 98% for F3 or higher (advanced fibrosis), and 85% for F2 or higher (significant fibrosis). Meng et al [50] achieved accuracy of 93.90% on 30% of their data set (n ¼ 279 cases: 79 normal, 89 early-stage fibrosis, 111 late-stage fibrosis) for predicting the stage of liver fibrosis. The AUC of the method proposed by Liu et al [51] for classifying a liver as normal or abnormal reached 96.8%, which is superior to the accuracy of low-level features. Wu et al [52] showed that their method outperforms

Table 1. Model characteristics for thyroid nodule detection and classification

| Study | Total Number of Images (Number of Patients) | Test Set Number of Images (Number of Patients) | Task | Method | Performance Metrics |
|-------------------------|---|--|----------------|-----------------------------------|---|
| Ma et al (2017) [29] | 15,000 (4,782) | 10-fold cross-validation | Classification | Two fused CNN models | Accuracy: 83.02% TPR: 82.41% TNR: 84.96% AUC: 89.30% |
| Ma et al (2017) [30] | 21,523 (5,842) | 10-fold cross-validation | Detection | Two cascaded CNN models | AUC: 98.51% |
| Li et al (2018) [31] | 4,670 (300) | 1,027 (100) | Detection | Faster R-CNN [32] | TPR: 93.5% TNR: 81.5% AUC: 93.8% |
| Li et al (2018) [33] | 332,180 (45,644) | 19,781 (2,692) | Classification | Resnet50 [34] and Darknet-19 [35] | Accuracy: 88.9% TPR: 92.2% TNR: 87.1% AUC: 94.7% |
| Akkus et al (2019) [16] | 300 (300) | 100 (50) | Classification | Inception [36] | TPR: 86% TNR: 90% |
| Choi et al (2017) [22] | 102 (89) | 102 (89) | Classification | Proprietary | Accuracy: 81.4% TPR: 90.7% |

| | | | | | |
|---------------------------|----------------|----------|----------------|--------------------------|---|
| | | | | | TNR: 74.6% AUC: 83% |
| Pereira et al (2018) [37] | 964 (165) | 193 (33) | Classification | CNN based on AlexNet [4] | Accuracy: 83% TPR: 95% TNR: 40% AUC: 80% |
| Chi et al (2017) [17] | 428 p 208 (NA) | 549 (61) | Classification | GoogLeNet [36] | Accuracy: 98% TPR: 99% TNR: 94% |

Note: AUC ¼ area under receiver operating characteristic curve; CNN ¼ convolutional neural network; NA ¼ not available; TNR ¼ true negative rate (specificity); TPR ¼ true positive rate (sensitivity).

Table 2. Model characteristics for breast lesion detection and classification

| Study | Total Number of Images (Number of Patients) | Test Set Number of Images (Number of Patients) | Task | Method | Performance Metrics |
|-------------------------|---|--|----------------|-----------------------------------|---|
| Byra et al (2018) [42] | 882 (NA) | 150 (150) | Classification | CNN based on VGG19 [43] | Accuracy: 88.7% TPR: 84.8% TNR: 89.7% AUC: 93.6% |
| Han et al (2017) [44] | 7,408 (5,151) | 829 (NA) | Classification | CNN based on GoogLeNet [36] | Accuracy: 91.23% TPR: 84.29% TNR: 96.07% AUC: 96.01% |
| Cheng et al (2016) [15] | 520 (520) | 10-fold cross-validation | Classification | Stacked denoising autoencoder [2] | Accuracy: 82.4% TPR: 78.7% TNR: 85.7% AUC: 89.6% |
| Zhang et al (2016) [45] | 227 (121) | 5-fold cross-validation | Classification | Proprietary | Accuracy: 93.4% TPR: 88.6% TNR: 97.1% |
| Yap et al (2018) [46] | 306 p 163 (NA) | 10-fold cross-validation | Detection | FCN-AlexNet [4] | TPF: 98% p 92% |
| Kumar et al (2018) [47] | 433 (258) | 61 (NA) | Segmentation | U-Net [48] | Dice: 82% TPF: 84% |

Note: AUC ¼ area under receiver operating characteristic curve; CNN ¼ convolutional neural network; NA ¼ not available; TNR ¼ true negative rate (specificity); TPF ¼ true positive fraction; TPR: true positive rate (sensitivity).

classical ML methods (accuracy 86.36% versus 66.67%-81.86%). Biswas et al [53] achieved performance superior to that of ML approaches (accuracy 82% [SVM] versus 92% [extreme learning machine (ELM)] versus 100% [DL]) in the assessment of fatty liver disease from ultrasound images using DL. According to the studies presented here, DL can significantly improve the diagnosis of liver diseases and could potentially reduce unnecessary liver biopsies and related health care costs.

Table 3. Model characteristics for liver lesion classification

| Study | Total Number of Images (Number of Patients) | Test Set Number of Images (Number of Patients) | Task | Method | Performance Metrics |
|------------------------|---|--|----------------|-----------------------------------|--|
| Wang et al (2018) [49] | 1,990 (398) | One-third of total | Classification | CNN on radiomic features from SWE | TPR: 69.1%-96.9% TNR: 88.0%-98.3% AUC: 85%-98% |
| Meng et al (2017) [50] | 1,674 (279) | 30% of total | Classification | CNN based on VGGNet [43] | Accuracy: 93.90% |
| Liu et al (2017) [51] | 91 (91) | 3-fold cross-validation | Classification | CNN & SVM classification | Accuracy: 89.2% AUC: 96.8% |
| Wu et al [52] | 22 (26) | 10-fold cross-validation | Classification | Restricted Boltzmann machine | Accuracy: 86.36% TPR: 83.33% TNR: 87.50% |
| Byra et al [54] | 55 (55) | Leave-one-out cross-validation | Classification | ResNet [34] | AUC: 97.7% |
| Biswas et al 2018 [53] | 63 (63) | 10-fold cross-validation | Classification | Inception [36] | Accuracy: 99% |

Note: AUC ¼ area under receiver operating characteristic curve; CNN ¼ convolutional neural network; SVM ¼ support vector machine; TNR ¼ true negative rate (specificity); TPR ¼ true positive rate (sensitivity).

Other Applications

The method proposed by Yu et al [55] for classification of fetal ultrasound plane obtained accuracy of 93.03%, which is superior to that of traditional ML methods. Wu et al [56] compared their CNN model with the subjective image quality assessment of three physicians and concluded that the performance of their model is comparable with the physicians’ ratings. The T-RNN model of Chen et al [57] achieved an AUC of 0.95 for detecting fetal standard plane from ultrasound videos. Menchón-Lara et al [58] obtained intima-media thickness measurements using a radial basis function network with acceptable errors compared with manual measurements. Lekadir et al [59] presented Pearson correlation coefficients of 0.92, 0.87, and 0.93 for lipid core, fibrous tissue, and calcified tissue, respectively, between areas calculated by an expert clinician and the proposed CNN model. The experiment indicates that the classification accuracy of CNNs is much better than that of SVMs. Hetherington et al [60] concluded that their model could accurately detect the vertebral level so that the anesthesiologist can find the right site to inject anesthetic. The trained VGGNet [43] of Cheng and Malhi [61] classified 77.9% of abdominal ultrasound images correctly on the test data set (1,109 of 1,423 images), which is comparable with a radiologist’s performance (71.7%).

IV. DISCUSSION AND OUTLOOK

Although DL methods for ultrasound provide promising results, AI-powered ultrasound is still far behind the progress in AI-powered CT and MRI because of high intra- and inter-reader variability in ultrasound image acquisition and interpretation.

Most of the DL applications in ultrasound were trained and evaluated on limited, single data sets obtained from a single medical center and a single ultrasound device. To overcome this limitation, transfer learning and fine-tuning a DL model previously trained on optical or natural-world images as previously proposed [42,50,61] can be applied. However, it would be more appropriate to apply transfer learning on a DL model trained natively on ultrasound images and fine-tune the model on a new data set obtained from a different medical center and/or a different ultrasound device. Another approach to overcome the limitation of having a limited data set is to use data augmentation (eg, tissue deformation, translations, horizontal flipping, adding noise, and enhancing images) to improve the generalization ability of DL models. However, data augmentation

parameters should be chosen cautiously to realistically mimic variations in ultrasound images. For example, vertically flipping ultrasound images will not be a realistic transformation, because shadowing never appears in the opposite direction of the ultrasound beam.

To build trust in an AI system designed for disease prediction from medical images, we must build transparent models that explain how and what they predict. Understanding the inner workings of a CNN requires interpreting the feature activity in each layer [67-69]. However, these activities become complex and abstract in deep CNN layers, and therefore it is more difficult to interpret them but usually results in more robust and generalizable features. By using DL models, we sacrifice interpretability for robustness and complex imaging features with greater generalization ability. The convolutional properties of CNN layers have been projected back to the input pixel space, showing what input pattern originally resulted in an activation in the feature maps. This explains which regions of the image play an important role in maximizing the classification accuracy. Several techniques have been used to investigate what DL sees and make CNN understandable, including deconvolutional networks [70], gradient back-propagation [71], class activation maps [72], gradient-weighted class activation maps [73], and saliency maps [74,75] for multiple CNN architectures [43,48,76-78]. This is an active area of research in the DL community.

Current DL models for ultrasound diagnosis use only 2-D cross-sectional images for making predictions. However, the information in 2-D cross-sections is limited and does not represent lesions completely. DL models trained on 3-D ultrasound data, ultrasound cine clips with multiple views of lesions, or spatiotemporal data could potentially improve the diagnostic accuracy of models and consider complete lesions. Furthermore, developing DL models that are trained on multimodal (B-mode, Doppler, contrast-enhanced ultrasound, and SWE) images, which provide complementary information to one another, could also improve the diagnostic accuracy of DL models.

In summary, AI-powered ultrasound systems that evaluate multimodal data, guide sonographers, and provide objective qualifications (eg, standard view of an organ and acceptable image quality), measurements, and diagnosis will not only assist with decision making but also improve ultrasound clinical workflow and reduce health care costs.

TAKE-HOME POINTS

- DL models that are trained on multimodal (B-mode, Doppler, contrast-enhanced ultrasound, and SWE) images, which provide complementary information to one another, could also improve the diagnostic accuracy of DL models.
- To build trust in an AI system designed for disease prediction from medical images, we must build transparent models that explain how and what they predict.
- The generalization ability of DL-based diagnosis approaches have been proved to be superior than traditional ML approaches.
- DL models trained on 3-D ultrasound data, ultrasound cine clips with multiple views of lesions, or spatiotemporal data could potentially improve the diagnostic accuracy of models and consider complete lesions.
- Providing guidance to operators with AI during data acquisition and measurement would make ultrasound more intelligent and less operator dependent.

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